

Introduction

• Summary of Part I

- In Part I, the R, QR and AvQR-based support estimation have been investigated
- R is the best support convex hull estimator in noise-free case
- But not necessarily in presence of a.o. outliers : only two extreme sample points are considered ! AvQR is thus better.

• Aim of part II

- For QR and AvQR: how to choose a meaningful value for m given N without a priori knowledge on the source pdfs ?
- What about a performance analysis based on separation performances viewpoint ?

Choosing m given N : approach

• Idea

The estimation error must be small at least in probability, i.e. find the largest m such that the following relation holds for sufficiently small error threshold ε and sufficiently close to but smaller than one probability threshold P_{thresh} :

$$\Pr(\mu[\Omega(Y_i)] - \langle R_m(Y_i) \rangle \leq \varepsilon) > P_{thresh} \quad (1)$$

• Method

- **Problem:** left hand side of (1) equals $1 - F_{\langle R_m(Y_i) \rangle}(\mu[\Omega(Y_i)] - \varepsilon)$ which depends on the output pdf f_{Y_i} , i.e. on the unknown source pdfs !
- **Solution:** Find a distribution-free lower bound \mathcal{L} for $\Pr(\cdot)$ in (1) and find the largest m such that $\mathcal{L} \geq P_{thresh}$

Choosing m given N : details

- Define the non-blind support estimation error based on quantile difference:

$$\varepsilon \doteq \mu[\Omega(X)] - (\xi_q - \xi_p) \quad (2)$$

$\Rightarrow p, q$ in $[0,1]$ control the estimation error ε

- Observe that $\langle R_m(X) \rangle \geq R_m(X)$ w.p. one

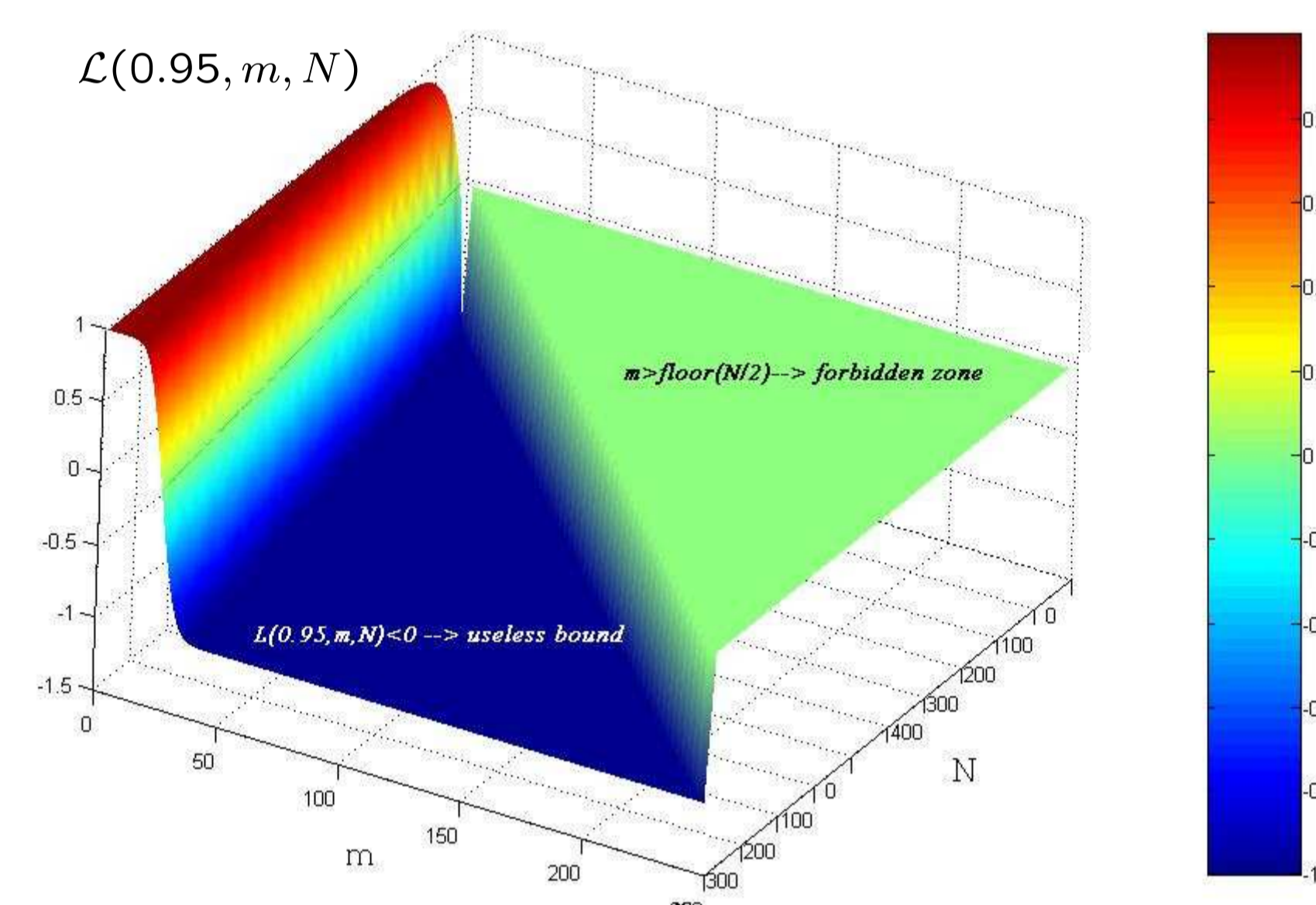
$$\begin{aligned} \Pr[\langle R_m(X) \rangle \geq \mu[\Omega(X)] - \varepsilon] &\geq \Pr[R_m(X) \geq \mu[\Omega(X)] - \varepsilon] \\ &= \Pr[R_m(X) \geq \xi_q - \xi_p] \\ &\geq \mathcal{L}(q, p, m, N) \end{aligned}$$

$\Rightarrow P_{thresh}$ controls confidence in support estimation

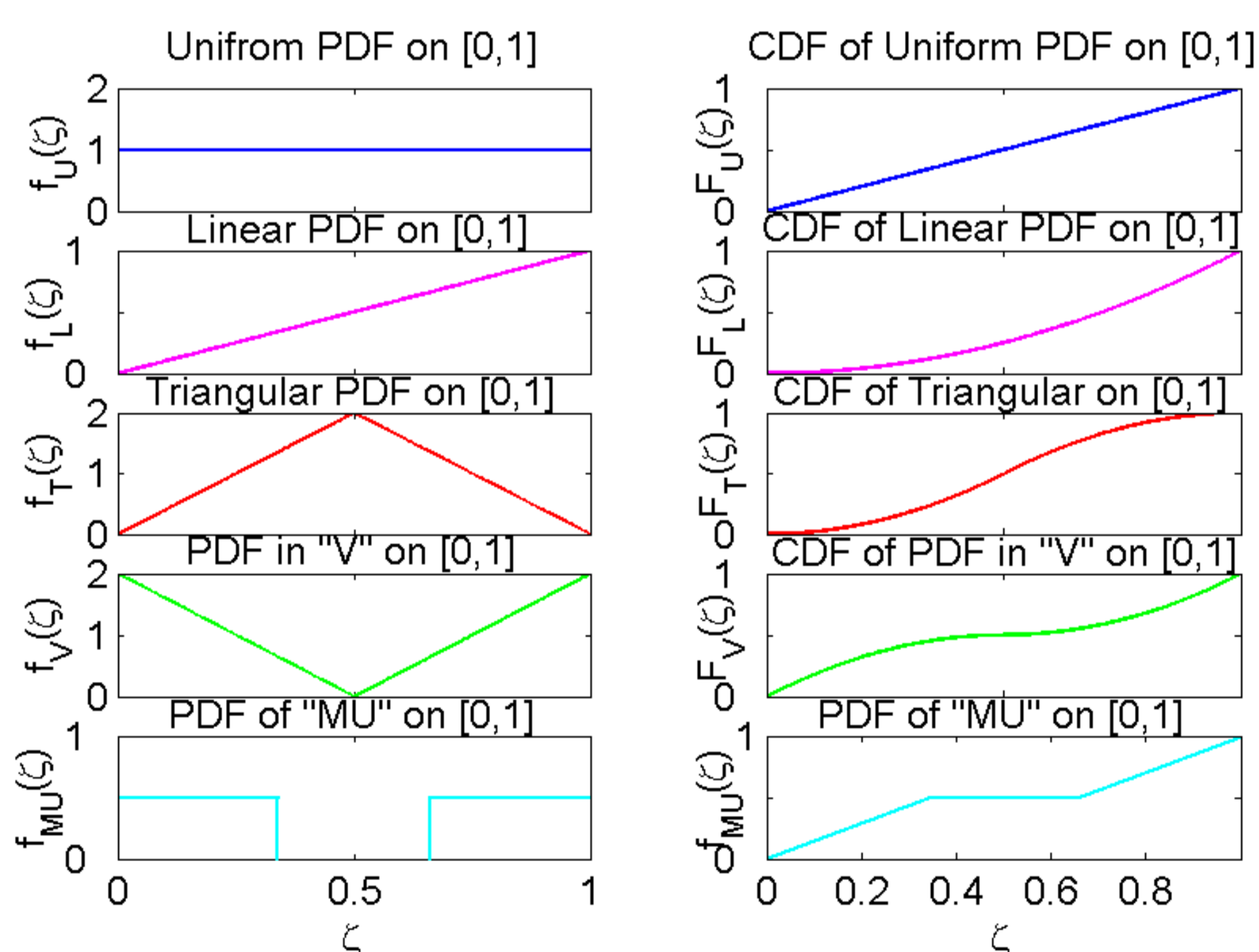
- Fix q close to one, $p = 1 - q$ and the probability threshold P_{thresh}
- Find the largest value m_0 of m ensuring that the lower bound $\mathcal{L}(\cdot)$ given by [Chu 1957] is higher than the desired threshold P_{thresh}
- Then (1) holds. This gives confidence in support estimation !

Towards a probabilistic relation $m(N)$

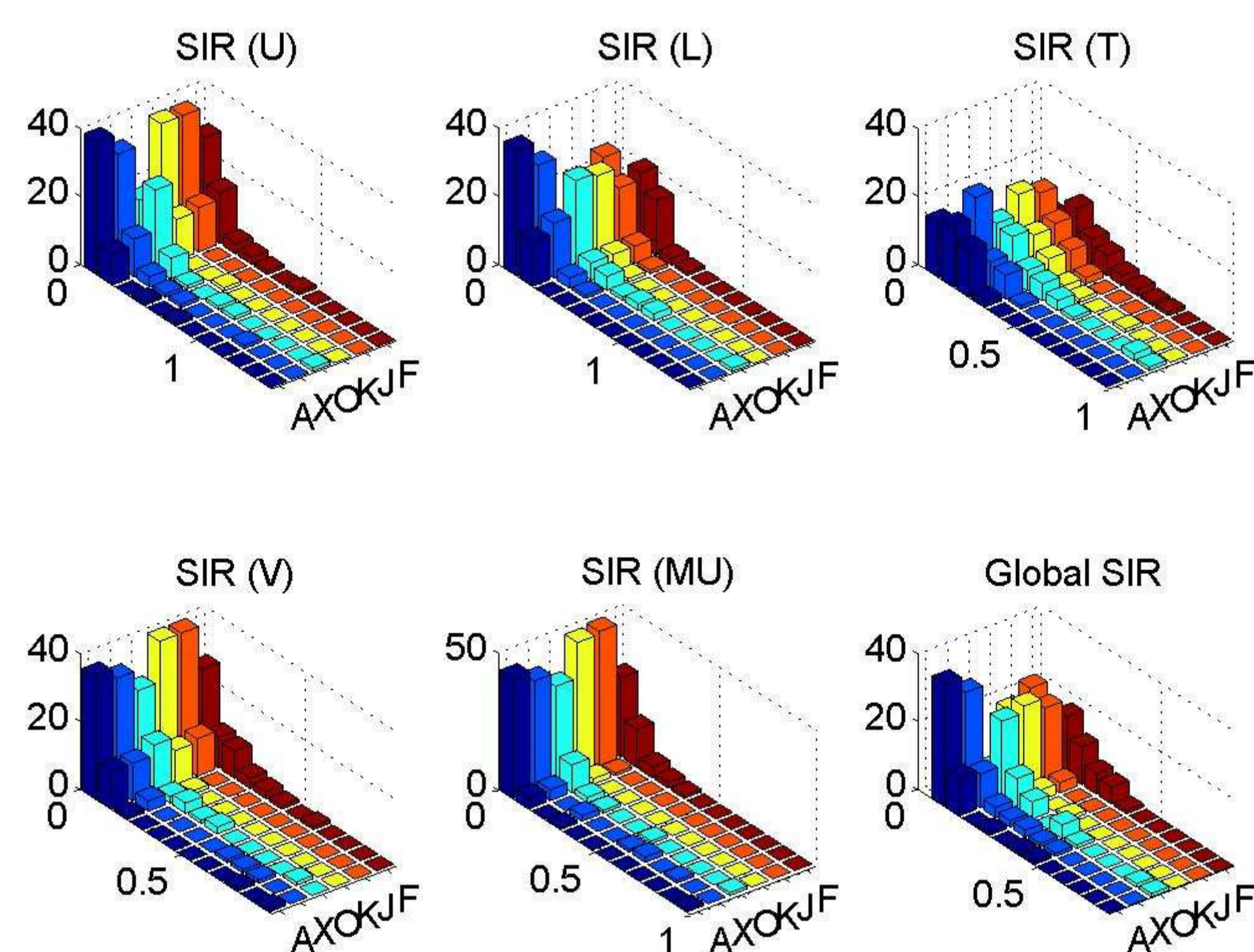
- If $\mathcal{L}(q, m_0, N) \geq P_{thresh}$ then (1) holds in the sense of (2) for all $m \leq m_0$
- Define $\mathcal{L}_+(q, m, N) = \max(0, \mathcal{L}(q, m, N))$



Source pdfs



Summary of results ($m=m\#(N)$)



- AvQR
- R
- QR
- Kurtosis
- Jade
- FastICA

Conclusion

- A blind and meaningful relation $m = m\#(N)$ can be provided and an empirical law can be derived (see paper for more details)
- With this rule, AvQR-ICA benefits from good separation performances

Main References

- Vrins et al., ICASSP 2005
- Chu, Ann. Math. Stat. 28, 1957
- David, "Order Statistics", 1970